

CR7 CR12 CR18 CR20

Specifications

Payload	7 kg	12 kg	18 kg	20 kg
Reach	850 mm	1,300 mm	925 mm	1,650 mm
Weight	About 27 kg	About 43 kg	About 40 kg	About 75 kg
Degrees of freedom	6	6	6	6
MTBF	> 50,000 h	> 50,000 h	> 50,000 h	> 50,000 h
Power supply	90-264VAC, 47-63Hz/48VDC			
Programming	Direct teaching control and graphical interface			

Performance

Power consumption	Average	Peak	Average	Peak	Average	Peak	Average	Peak
	500 w	1,500 w	600 w	2,000 w	600 w	2,000 w	1,000 w	3,000 w
Safety	Over 20 adjustable safety features including collision detection, virtual walls, and collaboration mode.							
Certification	EN ISO 13849-1, Cat.3, PL d, EN ISO 10218-1, and EU CE marking requirements							
Force sensing (tool flange)	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z
Force measurement resolution	0.1 N	0.02 Nm	0.1N	0.02Nm	0.1N	0.02Nm	0.1N	0.02Nm
Relative accuracy of force control	0.5 N	0.1 Nm	0.5N	0.1Nm	0.5N	0.1Nm	0.5N	0.1Nm
Adjustable range of Cartesian stiffness	0~3,000 N/m, 0~300 Nm/rad		0~3,000 N/m, 0~300 Nm/rad		0~3,000 N/m, 0~300 Nm/rad		0~3,000 N/m, 0~300 Nm/rad	
Operating temperature	0°C~45°C		0°C~45°C		0°C~45°C		0°C~45°C	
Humidity	≤ 93% RH (non-condensing)		≤ 93% RH (non-condensing)		≤ 93% RH (non-condensing)		≤ 93% RH (non-condensing)	

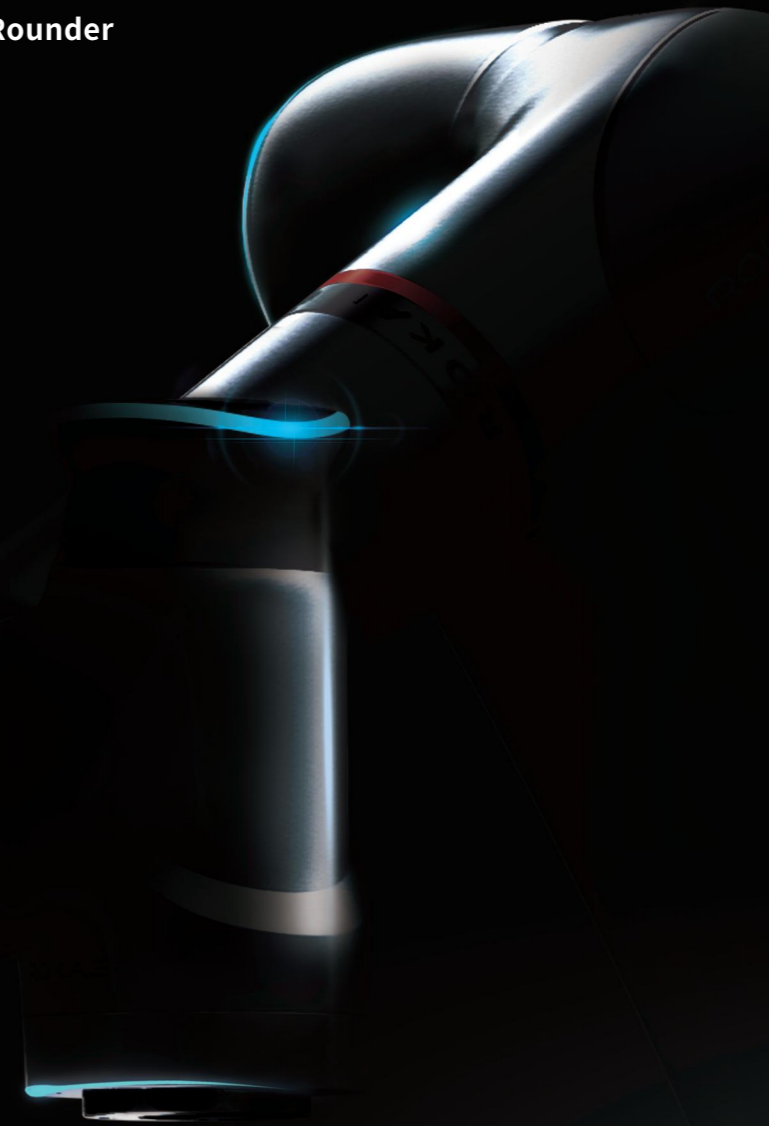
Motion

Repeatability	< ±0.03 mm		< ±0.03 mm		±0.03 mm		±0.05 mm	
Motion joint	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed
Axis 1	±175°	180°/s	±175°	120°/s	±175°	120°/s	±175°	120°/s
Axis 2	±175°	180°/s	±170°	120°/s	±170°	120°/s	±175°	120°/s
Axis 3	±175°	234°/s	±175°	180°/s	±165°	180°/s	±170°	120°/s
Axis 4	±175°	240°/s	±175°	234°/s	±175°	234°/s	±175°	234°/s
Axis 5	±175°	240°/s	±175°	240°/s	±175°	240°/s	±175°	234°/s
Axis 6	±175°	300°/s	±175°	240°/s	±175°	240°/s	±175°	234°/s
Axis 7	—		—		—		—	
Maximum speed at tool end	≤ 3.2 m/s		≤ 3 m/s		≤ 3 m/s		≤ 2.8 m/s	

Features

IP rating	IP54/IP67
ISO cleanroom class	5
Noise	≤ 70 dB(A)
Robot installation	At any angle
Tool I/O ports	2 Digital outputs, 2 Digital inputs, 2 Analog inputs
Tool communication interface	RS485
Tool I/O power supply	12V/24V 1A
Pedestal common I/O ports	4 Digital outputs, 4 Digital inputs, 4 safety I/O
Pedestal communication interface	1 channels Ethernet
Pedestal output power supply	24V, 1.5A

**CR** Series Flexible Collaborative Robots  
A Powerful Yet Flexible All-Rounder



ROKAE Robotics

400-010-8700  
www.rokae.com  
sales@rokae.com



# CR Series

## Flexible Collaborative Robots

The new **xMate CR** series flexible collaborative robots are built on the force-position hybrid control framework and xCore, a new self-developed high-performance control system for industrial robots. Designed for industrial applications, the robots deliver improved motion performance, force control, safety, ease of use, and reliability. This makes it an ideal choice for different applications in various industries, helping enterprises implement flexible production quickly.



**Model CR7**  
Payload 7kg  
Reach 850mm

**Model CR12**  
Payload 12kg  
Reach 1300mm

**Model CR18**  
Payload 18kg  
Reach 925mm

**Model CR20**  
Payload 20kg  
Reach 1650mm

## Applications

xMate CR series flexible collaborative robots can undertake a variety of tasks, including

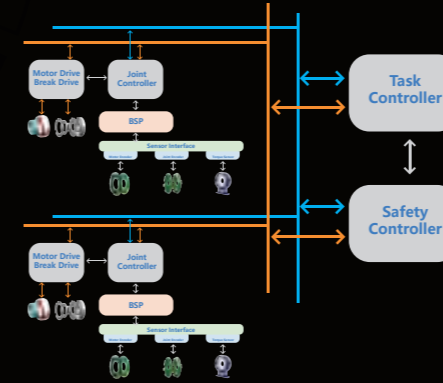
- compliant assembly
- screw locking
- inspection and measurement
- handling
- material removal
- gluing
- equipment care

driving improved productivity and flexible automation for companies of all sizes.



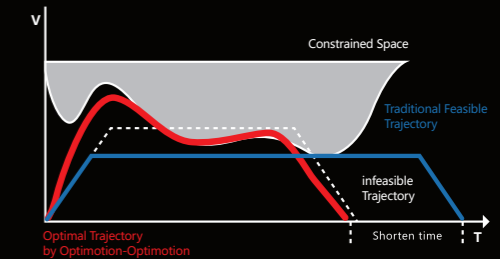
## Extreme Safety

Suction band-type brakes, independently certified safety controllers, over 20 certified safety features, and ultrasensitive collision detection by torque sensors, comprehensively ensure a safer human-machine collaboration.



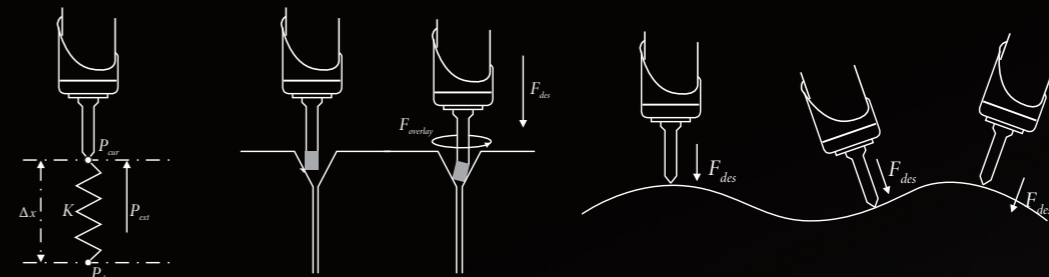
## Superior Performance

Cutting-edge motion control technologies for industrial robots to deliver first-class path accuracy, combined with customized motor drive control systems, create a powerful performance.



## Compliant Flexibility

By adopting force-position hybrid control technology, highly dynamic force control is integrated into robot joints, which provides compliance control close to human hands, while the force control process kit helps greatly enhance force control task efficiency with no additional extensions required.



## Ease of Use

Fast installation and flexible deployment thanks to the cabinet-free design, direct teaching control, and graphical programming enable greater ease of use. Applicable to a variety of application scenarios by supporting most extensions in the industrial ecosystem.



## Excellent Reliability

IP67 protection, 100+ design verification experiments, and 20+ factory tests, build them into an ideal choice for industrial applications.



A Powerful Yet Flexible All-Rounder |